

Object List BACnet MS/TP – Universal Field Controller FSC-UFC24

Version: Application Software Version 06.09.2017

| Object | Value | Description | R/W | Default | Remarks | Function Fire Damper in the UFC24 Software | Function Smoke Damper in the UFC24 Software |
|----------------------|---|---|-----|-----------|---|--|---|
| Binary Input # 0 | 1-On, 0-Off | DI1_ManualOverride-Physical Input | R | | read only | If the manual override is activated the relay is switched off, the power is interrupted and the damper is closing | If the manual override is activated the signal for the damper actuator is changed and the damper actuator is moving to the opposite position |
| Binary Input # 1 | 1-On, 0-Off | DI2_SmokeDetector-Physical Input | R | | read only | The smoke detector indicates alarm | The smoke detector indicates alarm |
| Binary Input # 2 | 1-On, 0-Off | DI3_ThermoElectric-Physical Input | R | | read only | The thermoelectric tripping device is activated - relay is switched off - the fire damper is closing | No functionality for the smoke damper, only message to the controller |
| Analog Output # 0 | 0-100 % | Status Controller | R | | Always available, even operated on a bus system | | |
| Binary Output # 0 | 1-On, 0-Off | LED_Close | R | | Indication LED | | |
| Binary Output # 1 | 1-On, 0-Off | LED_Open | R | | Indication LED | | |
| Binary Output # 2 | 1-On, 0-Off | LED_Status | R | | Indication LED | | |
| Binary Output # 3 | 1-On, 0-Off | LED_Error | R | | Indication LED | | |
| Binary Output # 4 | 1-On, 0-Off | Relay Damper | R/W | 0-Off | Relay in the UFC indicating power | If relay off - actuator is moving to open position, if relay on - damper closing, if power off - damper closing (spring) | If relay on (power) the damper is moving over the end switch and goes back to close position. Once UFC24 got a control signal - this is stored and the smoke damper, after power loss, will always move to the position of the last command, as soon as the power is back. |
| Analog Value # 0 | 0...180 Sec | DI1_ManualOverride_OnDelay | R/W | 0 | | Delay functionality | |
| Analog Value # 1 | 0...180 Sec | DI2_SmokeDetector_OnDelay | R/W | 0 | | | |
| Analog Value # 2 | 0...180 Sec | DI3_ThermoElectric_OnDelay | R/W | 0 | | | |
| Analog Value # 3 | 960-1920-3840-7680 | BaudRate | R | | Auto detect | | |
| Analog Value # 4 | 0-50-100 % | DamperPosition | R | | Indicates damper position | 0% = damper actuator end switch closed is active; 50% = no damper actuator switch is activated; actuator is moving or stands between the end switches; 100% = damper actuator end switch open is active | 0% = damper actuator end switch closed is active; 50% = no damper actuator switch is activated; actuator is moving or stands between the end switches; 100% damper actuator end switch open is active |
| Analog Value # 5 | 0...360 Sec | DamperCheckTime | R/W | 90-Sec | Time to control running time of the actuator between the end switches, can be adapted. | Command by the controls that the actuator has to close/open. If the actuator does not reach the other end switch within the dedicated time an error message is sent. Automatic run time test done by activating the automatic test run - see detailed description of BV# 15. | Command by the controls that the actuator has to close/open. If the actuator does not reach the other end switch within the dedicated time an error message is sent. Automatic run time test done by activating the automatic test run - see detailed description of BV# 15. |
| Analog Value # 6 | 1...8 | System Status | R | | | | |
| Analog Value # 7 | 0...1024 | InternalParameters | R | | | | |
| Analog Value # 8 | 804XXX | Device Instant | R/W | | | | |
| Analog Value # 9 | 0...360 | Delay Alarm Communication | R/W | 120-Sec | Bus monitoring delay | If AV# 10 is activated, the damper will move into close position after the time indicated (sec) at AV# 9 and remain there until the bus communication comes back | No functionality for the smoke damper |
| Analog Value # 10 | 0..1 | Logic Alarm Communication | R/W | 0-Disable | Bus monitoring on / off | If AV# 10 activated (1) the damper will move into close position after the time indicated (sec) at AV# 9 and remains there until the bus communication comes back. If not activated the damper remains in open position until triggered from any other source (thermoel. tripping device, smoke detector, digital input) | No functionality for the smoke damper |
| Binary Value # 0 | 1-On, 0-Off | DI1_ManualOverride_Normally Close/Open | R/W | 0-N.Open | digitally open/close damper | If the manual override is activated the relay is switched off, the power is interrupted and the damper is closing | If the manual override is activated the signal for the damper actuator is changed and the damper actuator is moving to the opposite position. In case of power loss the last command is stored. As soon as the power is back the actuator will continue to move to the position of the last command |
| Binary Value # 1 | 1-On, 0-Off | DI2_SmokeDetector_Normally Close/Open | R/W | 1-N.Close | Position can be changed by software. UFC24 will be delivered with a jumper (bridge) as plug and play solution | The smoke detector indicates alarm - the signal is sent to the controller. With dip switch no. 7 one can choose whether the signal is only sent to the controller (as UFC24) and the set up in the controller will start any activities (dip switch off) or whether the actuator connected to the UFC24 will close immediately (dip switch on) . | The smoke detector indicates alarm to the controller. For smoke detection always the controller has to give the command. Dip switch no. 7 does not have any functionality for smoke extraction. |
| Binary Value # 2 | 1-On, 0-Off | DI3_ThermoElectric_Normally Close/Open | R/W | 1-N.Close | Position can be changed by software. UFC24 will be delivered with a jumper (bridge) as plug and play solution | The thermoelectric tripping device is activated - relay is switched off - the fire damper is closing | No functionality for the smoke damper, only message to the controller |
| Binary Value # 3 | 1-On, 0-Off | Dip Switch Selection – Fire Application | R | | Selection functionality on Conf dip switch bar | | |
| Binary Value # 4 | 1-On, 0-Off | Dip Switch Selection – Smoke Application | R | | Selection functionality on Conf dip switch bar | | |
| Binary Value # 5 | 1-On, 0-Off | Dip Switch Selection – Bus Application | R | | Selection functionality on Conf dip switch bar | | |
| Binary Value # 6 | 1-On, 0-Off | Dip Switch Selection - Analogue Application | R | | Selection functionality on Conf dip switch bar | | |
| Binary Value # 7 | 1-On, 0-Off | ManualOverride_Effective | R | | Shows the real position | | |
| Binary Value # 8 | 1-On, 0-Off | SmokeDetector_Effective | R | | Shows the real position | | |
| Binary Value # 9 | 1-On, 0-Off | ThermoElectric_Effective | R | | Shows the real position | | |
| Binary Value # 10 | 1-On, 0-Off | DamperMoving | R | | Damper is between the two end switches | | |
| Binary Value # 11 | 1-On, 0-Off | TestButton | R | | Test button on the UFC24 for on-site testing | - Power on the UFC24: actuator (damper) opening until end position is reached - Pushing test button will interrupt the power supply (UFC24 relay) to the actuator. Spring is closing the actuator - As soon as test button is released the power comes back and the damper will open again | - Pushing test button: the smoke damper is moving in the opposite direction - release the test button: the smoke damper is moving back into original position |
| Binary Value # 12 | 1-On, 0-Off | Damper Close | R | | Feedback damper position, indicated by the end switches of the actuator | | |
| Binary Value # 13 | 1-On, 0-Off | Damper Open | R | | Feedback damper position, indicated by the end switches of the actuator | | |
| Binary Value # 14 | 1-On, 0-Off | Dip Switch - SelectTwoOnelInputPosition | R | | Dip switch for one actuator, end switch functionality is activated | | |
| Binary Value # 15 | 1-On, 0-Off | FullAutoTest | R/W | 0-Off | Activation of a full automatic test run of the actuator | The fire damper actuator is closing (spring) and remains in the closed position as long as the damper check time is set. After the time passed the actuator will open again until the end switch has been reached. If one of the end switches is not reached within the damper test time (AV# 5) - an error message is sent. | The smoke extraction actuator is moving to the opposite direction and remains in that position as long as the damper check time is set (i.e. 90 sec = the process has to be finished after 90 seconds) . After the time passed the actuator will move back to the original position until the end switch has been reached (90 seconds for the 2nd move again). If one of the end switches is not reached within the damper test time (AV# 5) in a test move - an error message is sent. |
| Binary Value # 16 | 1-On, 0-Off | Dip Switch Smoke Alarm Enable | R | | Dip Switch no 7 - functionality see BV# 17 | The smoke detector indicates alarm - the signal is sent to the controller. With dip switch no. 7 one can choose whether the signal is only sent to the controller and the set up in the controller will start any activities (dip switch off) or whether the actuator connected to the UFC24 will close immediately (dip switch on) . | The smoke detector indicates alarm to the controller. For smoke detection always the controller has to give the command. Dip switch no. 7 does not have any functionality for smoke extraction. |
| Binary Value # 17 | 1-On, 0-Off | Smoke Alarm Enable | R/W | 0-Off | Set same functionality as dip switch no. 7 by software | The smoke detector indicates alarm - the signal is sent to the controller. With dip switch no. 7 one can choose whether the signal is only sent to the controller and the set up in the controller will start any activities (dip switch off) or whether the actuator connected to the UFC24 will close immediately (dip switch on) . | The smoke detector indicates alarm to the controller. For smoke detection always the controller has to give the command. Dip switch no. 7 does not have any functionality for smoke extraction. |
| Binary Value # 18 | 1-On, 0-Off | Smoke Alarm Enable Effective | R | | Shows the real position of dip switch No. 7 | | |
| Binary Value # 19 | 1-On, 0-Off | SetFactoryDefault | R/W | 0 | If activated all settings are going back to factory default values | | |
| Binary Value # 20 | 1-On, 0-Off | Clear Message | R/W | 0 | Reset messages indicated | | |
| Multistate Value # 0 | 9600-19200-38400-76800 | BaudRate | R | | | | |
| Multistate Value # 1 | 1. Normal 2. Actuator Not Reach End Position 3. Smoke Detector On 4. Tripping On 5. Any Other Error 6. Test In Progress 7. Test Report Normal 8. Test Report Error | Status Controller | R | | Indicates normal position. It is not an error message but belongs as normal or standard value into this list | | |
| | | | R | | Indicates that the actuator has not reached the end position, the upper end switch of the actuator is not activated | | |
| | | | R | | Smoke detector input has been triggered, alarm message sent to the building automation system, if dip switch 7 is activated the damper is closing | | |
| | | | R | | Thermo el tripping device has been triggered, damper closed | | |
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